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| <input type="checkbox"/> | L5 | patient environment and operator | | 108 |
| <input type="checkbox"/> | L4 | patient environment and operator environment | | 0 |
| <input type="checkbox"/> | L3 | patient environment and operator environment and video and audio | | 0 |
| <input type="checkbox"/> | L2 | patient environment and operator environment and video and audio and control\$3 and robot6 | | 0 |
| <input type="checkbox"/> | L1 | robot\$6 and three wheel and computer and camera | | 65 |

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| <input type="checkbox"/> | L5 | video and audio and L4 | 43 |
| <input type="checkbox"/> | L4 | network and L3 | 157 |
| <input type="checkbox"/> | L3 | station and mobile robot | 443 |
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| <input type="checkbox"/> | L8 | (5971976 6063095 6007550 6436107 6728599 6852107 10/067730).pn. | 13 |
| <input type="checkbox"/> | L7 | L4 and camera | 9 |
| <input type="checkbox"/> | L6 | L4 and camera and conferencing | 1 |
| <input type="checkbox"/> | L5 | L4 and robot\$6 | 4 |
| <input type="checkbox"/> | L4 | patient environment and operator. | 107 |
| <input type="checkbox"/> | L3 | patient environment and operator environment | 0 |
| <input type="checkbox"/> | L2 | patient environment and operator environment and video and audio | 0 |
| <input type="checkbox"/> | L1 | patient environment and operator environment and video and audio and control\$3 and robot6 | 0 |

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| <input type="checkbox"/> | L3 | robot\$6 and L2 | 189 |
| <input type="checkbox"/> | L2 | camera and L1 | 276 |
| <input type="checkbox"/> | L1 | minimally invasive surgery and remote | 596 |

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minimally invasive surgery

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1 Robotics in minimally invasive surgery

Davies, B.;

Through the Keyhole: Microengineering in Minimally Invasive Surgery, IEE Colloquium on , 6 Jun 1995

Pages:5/1 - 5/2

[Abstract] [PDF Full-Text (124 KB)] IEEE CNF

2 Hyper redundant miniature manipulator "Hyper Finger" for remote minimally invasive surgery in deep area

Ikuta, K.; Hasegawa, T.; Daifu, S.;

Robotics and Automation, 2003. Proceedings. ICRA '03. IEEE International Conference on , Volume: 1 , 14-19 Sept. 2003

Pages:1098 - 1102 vol.1

[Abstract] [PDF Full-Text (388 KB)] IEEE CNF

3 A force reflective master-slave system for minimally invasive surgery

Tavakoli, M.; Patel, R.V.; Moallem, M.;

Intelligent Robots and Systems, 2003. (IROS 2003). Proceedings. 2003 IEEE/RSJ International Conference on , Volume: 4 , 27-31 Oct. 2003

Pages:3077 - 3082 vol.3

[Abstract] [PDF Full-Text (720 KB)] IEEE CNF

4 Dual use applications of Wright Laboratory Avionics Technologies to computer assisted minimally invasive surgery (CAMIS)

Williams, R.;

Aerospace and Electronics Conference, 1994. NAECON 1994., Proceedings of the IEEE 1994 National , 23-27 May 1994

Pages:1248 - 1251 vol.2

[Abstract] [PDF Full-Text (276 KB)] IEEE CNF

5 Controlling miniature robotic systems in minimally invasive surgery

Wapler, M.; Neugebauer, J.;

Intelligent Robots and Systems '94. 'Advanced Robotic Systems and the Real World', IROS '94. Proceedings of the IEEE/RSJ/GI International Conference on , Volume: 1 , 12-16 Sept. 1994

Pages:711 - 716 vol.1

[\[Abstract\]](#) [\[PDF Full-Text \(364 KB\)\]](#) [IEEE CNF](#)

6 Minimally invasive surgery and technology

Fiennes, A.G.T.W.;

Technology in Medicine: Has Practice Met the Promise? (Digest No. 1996/177), IEE Colloquium on , 7 Oct. 1996

Pages:2/1 - 2/3

[\[Abstract\]](#) [\[PDF Full-Text \(236 KB\)\]](#) [IEE CNF](#)

7 Force controlled and teleoperated endoscopic grasper for minimally invasive surgery-experimental performance evaluation

Rosen, J.; Hannaford, B.; MacFarlane, M.P.; Sinanan, M.N.;

Biomedical Engineering, IEEE Transactions on , Volume: 46 , Issue: 10 , Oct. 1999

Pages:1212 - 1221

[\[Abstract\]](#) [\[PDF Full-Text \(444 KB\)\]](#) [IEEE JNL](#)

8 Applications of micromechatronics in minimally invasive surgery

Tendick, F.; Sastry, S.S.; Fearing, R.S.; Cohn, M.;

Mechatronics, IEEE/ASME Transactions on , Volume: 3 , Issue: 1 , March 1998

Pages:34 - 42

[\[Abstract\]](#) [\[PDF Full-Text \(144 KB\)\]](#) [IEEE JNL](#)

9 Surgery benefits from defense technology: dual use applications of Wright Laboratory Avionics technologies to Computer Assisted Minimally Invasive Surgery (CAMIS)

Williams, R.; Leonard, J.;

Aerospace and Electronic Systems Magazine, IEEE , Volume: 9 , Issue: 10 , Oct. 1994

Pages:3 - 6

[\[Abstract\]](#) [\[PDF Full-Text \(324 KB\)\]](#) [IEEE JNL](#)

10 Application of combined methods of imaging in minimally invasive surgery

Cysewska-Sobusiak, A.R.; Sowier, A.; Skrzypanek, P.;

Engineering in Medicine and Biology Society, 2003. Proceedings of the 25th Annual International Conference of the IEEE , Volume: 2 , 17-21 Sept. 2003

Pages:1043 - 1046 Vol.2

[\[Abstract\]](#) [\[PDF Full-Text \(488 KB\)\]](#) [IEEE CNF](#)

11 A medical robotic assistant for minimally invasive surgery

Munoz, V.F.; Vara-Thorbeck, C.; DeGabriel, J.G.; Lozano, J.F.; Sanchez-Badajoz, E.; Garcia-Cerezo, A.; Toscano, R.; Jimenez-Garrido, A.;

Robotics and Automation, 2000. Proceedings. ICRA '00. IEEE International Conference on , Volume: 3 , 24-28 April 2000

Pages:2901 - 2906 vol.3

[\[Abstract\]](#) [\[PDF Full-Text \(560 KB\)\]](#) [IEEE CNF](#)

12 Human-machine interfaces for minimally invasive surgery

Tendick, F.; Cavusoglu, M.C.;

Engineering in Medicine and Biology society, 1997. Proceedings of the 19th Annual International Conference of the IEEE , Volume: 6 , 30 Oct.-2 Nov. 1997
Pages:2771 - 2776 vol.6

[\[Abstract\]](#) [\[PDF Full-Text \(604 KB\)\]](#) [IEEE CNF](#)

13 Sensors and devices to enhance the performances of a minimally invasive surgery tool for replicating surgeon's haptic perception of the manipulated tissues

Scilingo, E.P.; De Rossi, D.; Bicchi, A.; Iacconi, P.;

Engineering in Medicine and Biology society, 1997. Proceedings of the 19th Annual International Conference of the IEEE , Volume: 3 , 30 Oct.-2 Nov. 1997
Pages:961 - 964 vol.3

[\[Abstract\]](#) [\[PDF Full-Text \(276 KB\)\]](#) [IEEE CNF](#)

14 Telemanipulator design for minimally invasive surgery

Lazeroms, M.; Jongkind, W.; Honderd, G.;

American Control Conference, 1997. Proceedings of the 1997 , Volume: 5 , 4-6 June 1997
Pages:2982 - 2986 vol.5

[\[Abstract\]](#) [\[PDF Full-Text \(468 KB\)\]](#) [IEEE CNF](#)

15 An articulated manipulator for enhanced dexterity in minimally invasive surgery

Mukherjee, R.; Song, G.; Satava, R.;

Engineering in Medicine and Biology Society, 1996. Bridging Disciplines for Biomedicine. Proceedings of the 18th Annual International Conference of the IEEE , Volume: 1 , 31 Oct.-3 Nov. 1996
Pages:220 - 222 vol.1

[\[Abstract\]](#) [\[PDF Full-Text \(296 KB\)\]](#) [IEEE CNF](#)

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Through the Keyhole: Microengineering in Minimally Invasive Surgery, IEE Colloquium on , 6 Jun 1995

Pages:5/1 - 5/2

IEEE CNF**2 Hyper redundant miniature manipulator "Hyper Finger" for remote minimally invasive surgery in deep area***Ikuta, K.; Hasegawa, T.; Daifu, S.;*

Robotics and Automation, 2003. Proceedings. ICRA '03. IEEE International Conference on , Volume: 1 , 14-19 Sept. 2003

Pages:1098 - 1102 vol.1

IEEE CNF**3 A force reflective master-slave system for minimally invasive surgery***Tavakoli, M.; Patel, R.V.; Moallem, M.;*

Intelligent Robots and Systems, 2003. (IROS 2003). Proceedings. 2003 IEEE/RSJ

International Conference on , Volume: 4 , 27-31 Oct. 2003

Pages:3077 - 3082 vol.3

IEEE CNF**4 Dual use applications of Wright Laboratory Avionics Technologies to computer assisted minimally invasive surgery (CAMIS)***Williams, R.;*

Aerospace and Electronics Conference, 1994. NAECON 1994., Proceedings of the IEEE 1994 National , 23-27 May 1994

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IEEE CNF**5 Controlling miniature robotic systems in minimally invasive surgery***Wapler, M.; Neugebauer, J.;*

Intelligent Robots and Systems '94. 'Advanced Robotic Systems and the Real World', IROS '94. Proceedings of the IEEE/RSJ/GI International Conference on , Volume: 1 , 12-16 Sept. 1994

Pages:711 - 716 vol.1

IEEE CNF**6 Minimally invasive surgery and technology***Fiennes, A.G.T.W.;*

Technology in Medicine: Has Practice Met the Promise? (Digest No. 1996/177), IEE Colloquium on , 7 Oct. 1996

Pages:2/1 - 2/3

IEEE CNF**7 Force controlled and teleoperated endoscopic grasper for minimally invasive surgery-experimental performance evaluation**

Rosen, J.; Hannaford, B.; MacFarlane, M.P.; Sinanan, M.N.;

Biomedical Engineering, IEEE Transactions on , Volume: 46 , Issue: 10 , Oct. 1999

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IEEE JNL**8 Applications of micromechatronics in minimally invasive surgery**

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Pages:34 - 42

IEEE JNL**9 Surgery benefits from defense technology: dual use applications of Wright Laboratory Avionics technologies to Computer Assisted Minimally Invasive Surgery (CAMIS)**

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Pages:3 - 6

IEEE JNL**10 Application of combined methods of imaging in minimally invasive surgery**

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Garcia-Cerezo, A.; Toscano, R.; Jimenez-Garrido, A.;

Robotics and Automation, 2000. Proceedings. ICRA '00. IEEE International Conference on , Volume: 3 , 24-28 April 2000

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Pages:2771 - 2776 vol.6

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Scilingo, E.P.; De Rossi, D.; Bicchi, A.; Iacconi, P.;

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Pages:961 - 964 vol.3

IEEE CNF**14 Telemanipulator design for minimally invasive surgery**

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American Control Conference, 1997. Proceedings of the 1997 , Volume: 5 , 4-6 June 1997

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IEEE CNF**15 An articulated manipulator for enhanced dexterity in minimally invasive surgery**

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Engineering in Medicine and Biology Society, 1996. Bridging Disciplines for Biomedicine. Proceedings of the 18th Annual International Conference of the IEEE , Volume: 1 , 31 Oct.-3 Nov. 1996

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Fernandez, L.; Sanchez, J.A.; Flores, A.;
Groupware, 2000. CRIWG 2000. Proceedings. Sixth International Workshop on , 18-20 Oct. 2000
Pages:150 - 153

IEEE CNF**2 Web component development for satellite imagery internet service system**

Jong-Hyun Park; Chung-Hyun Ahn; Kyoung-Ok Kim; Young-Kyu Yang;
Geoscience and Remote Sensing Symposium, 2001. IGARSS '01. IEEE 2001 International , Volume: 4 , 9-13 July 2001
Pages:1948 - 1950 vol.4

IEEE CNF**3 ZEUS: a CORBA framework for service location and creation**

Shankaran, N.; Klefstad, R.;
Applications and the Internet Workshops, 2004. SAINT 2004 Workshops. 2004 International Symposium on , 26-30 Jan. 2004
Pages:382 - 387

IEEE CNF**4 Adapting information presentation and retrieval through user modelling**

Bogonikolos, N.; Makris, C.; Tsakalidis, A.; Vassiliadis, B.;
Information Technology: Coding and Computing, 2001. Proceedings. International Conference on , 2-4 April 2001
Pages:399 - 404

IEEE CNF**5 "ARCHIMIDES": an intelligent agent for adaptive-personalized navigation within a WEB server**

Bogonikolos, N.; Fragoudis, D.; Likothanassis, S.;
System Sciences, 1999. HICSS-32. Proceedings of the 32nd Annual Hawaii International Conference on , Volume: Track5 , 5-8 Jan. 1999
Pages:9 pp.

IEEE CNF**6 Techniques for developing and measuring high performance Web servers over high speed networks**

Hu, J.C.; Mungee, S.; Schmidt, D.C.;
INFOCOM '98. Seventeenth Annual Joint Conference of the IEEE Computer and Communications Societies. Proceedings. IEEE , Volume: 3 , 29 March-2 April 1998
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IEEE CNF

7 Measuring the impact of event dispatching and concurrency models on Web server performance over high-speed networks

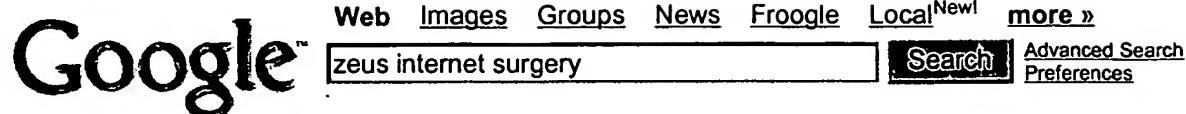
Hu, J.C.; Pyarali, I.; Schmidt, D.C.;

Global Telecommunications Conference, 1997. GLOBECOM '97., IEEE , Volume: 3 , 3-8

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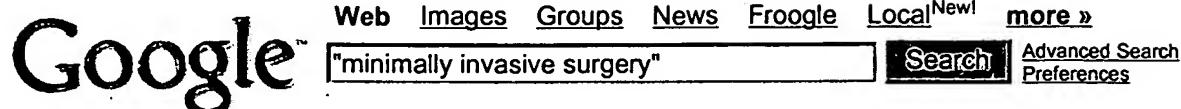
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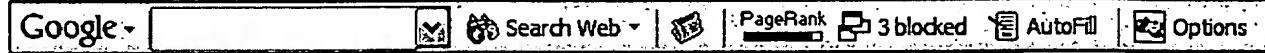
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